Environment as a Spatial Constraint on the Growth of Structural Form

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Some Informal Questions...

- Does the genome of a tree encode the information that the top is skinny and the bottom fat?
- Do the genes controlling the development of a circulatory system encode a description of the organism's overall morphology?

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Role of Genes

- Bilaterals: bilaterally symmetric morphology, vascular system for blood
- Echinoderms: radial symmetry, vascular system for water
- Homeodomain associated with the development of the vascular system underwent radical changes in role and expression domain between Echinoderms and their bilateral ancestors (Lowe and Wray, Nature, 1997)

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Motivations

We seek to use environment explicitly in Artificial Embryogeny (AE) to:

- Explore alternatives to fitness functions in AE
- Re-use genetic information in different environments
- Pose questions regarding genetic robustness relative to environment

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The Deva Model

Consists of:

- ▶ A Developmental Space, $D \subset \mathbb{Z}^2$, with discrete time
- A set of cell types (colours) C, $|C| = n_c$
- A set of cell actions A
- A transition function, φ : N → A, where N is a description of a neighbourhood of cells from C.

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More Deva Model

- Starting from a single cell in D, the cells execute actions from A, leading to some sort of growth.
- Actions include: Nothing, Die, Divide, Specialize(x), Elongate

Clicky.



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The Domain of Application: Structural Design



Trusses

- Simple models of structure
- Good approximations of bridges, towers, etc.
- Often form initial design stage of construction



Plane Trusses

- Consist of beams, joints, grounds.
- Want: stability, ability to withstand (distribute) external force.
- Can compute stability, pressure, displacement through system of linear equations (O(n³))



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Interpretation of Deva Growth

- ▶ We can map from a lattice of cell colours to a Plane Truss
- We can interpret Deva as a means of growing Plane Trusses developmentally
- Deva genomes can be evolved by using fitness to select for good Trusses

(Kowaliw et al; IEEE-Alife 2007)

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Evolved Trusses

Fitness function 1



Fitness Function 2



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Cheaters!



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Environment Experiments

- We define several types of environment
- We can evolve organisms in some environment, at some phenotypic size
- We can then re-grow organisms at different sizes, in different environments

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Environments



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Some Successful Organisms...

We evolved stable trusses capable of supporting external load in nearly all environments



Phenotypic Re-growth

- Deva model specifies a maximum amount of resources that development has available
- We evolved genomes at some maximum size (max height 30m)
- How well do our genomes adapt when given additional resources? (max height 40m)

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Phenotypic Re-growth Visual



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Phenotypic Re-growth Comparative



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Environmental Re-growth

- Any given evolutionary run takes place in a particular environment
- How well do our genomes adapt to previously unseen environments?

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Environmental Re-growth Comparative

No significant difference between random and re-grown genomes. Much variance in data!



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Phenotypic Re-growth Unsuccessful Visual

Many organisms overspecialized, performed far more poorly than random genomes in all novel environments.



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Phenotypic Re-growth Successful Visual (Zelig)

Some genomes performed well in nearly all environments.



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Environment as Spatial Constraint



- Zelig performed well in all environments in which evolution was successful generally (nine of ten)
- ▶ 7 used rules in the genome (compared with average 10-12)
- Similar appearance in all environments, adapting to fit provided space

Clicky 1. Clicky 2.

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Zelig



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Summary of Results

- Environment may be used as a spatial constraint, easily achieving goals which may be difficult with a fitness function
- Genomes may be re-used in environments other than the ones in which they evolved
- Deva genomes tend to be resistant to changes in phenotypic size
- Deva genomes are sometimes resistant to changes in environment, although usually not
- Some Deva genomes have been found which grow successful agents in nearly all environments

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